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The author team that established its reputation nearly twenty years ago with Fundamentals of Computer Algorithms offers this new title, available in both pseudocode and C++ versions. Ideal for junior/senior level courses in the analysis of algorithms, this well-researched text takes a theoretical approach to the subject, creating a basis for more in-depth study and providing opportunities for hands-on learning. Emphasizing design technique, the text uses exciting, state-of-the-art examples to illustrate design strategies.

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This book provides a full-scale presentation of all methods and techniques available for the solution of the Knapsack problem. This most basic combinatorial optimization problem appears explicitly or as a subproblem in a wide range of optimization models with backgrounds such diverse as cutting and packing, finance, logistics or general integer programming. This monograph spans the range from a comprehensive introduction of classical algorithmic methods to the unified presentation of the most recent and advanced results in this area many of them originating from the authors. The chapters dealing with particular versions and extensions of the Knapsack problem are self-contained to a high degree and provide a valuable source of reference for researchers. Due to its simple structure, the Knapsack problem is an ideal model for introducing solution techniques to

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students of computer science, mathematics and economics. The first three chapters give an in-depth treatment of several basic techniques, making the book also suitable as underlying literature for courses in combinatorial optimization and approximation.

This is the thoroughly revised and updated edition of the text that helped establish computer algorithms as a discipline of computer science. Using the popular object-oriented language C++, the text incorporates the latest research and state-of-the-art applications, bringing this classic to the forefront of modern computer science education. A major strength of this text is its focus on design techniques rather than on individual algorithms.

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Most industrial robots today have little or no sensory capability. Feedback is limited to information about joint positions, combined with a few interlock and timing signals. These robots can function only in an environment where the objects to be manipulated are precisely located in the proper position for the robot to grasp (i. e. , in a structured environment). For many present industrial applications, this level of performance has been adequate. With the increasing demand for high performance sensor-based robot manipulators in assembly tasks, meeting this demand and challenge can only be achieved through the consideration of: 1) efficient acquisition and processing of internal\external sensory information, 2) utilization and integration of sensory information from various sensors (tactile, force, and vision) to acquire knowledge in a changing environment, 3)

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exploitation of inherent robotic parallel algorithms and efficient VLSI architectures for robotic computations, and finally 4) system integration into a working and functioning robotic system. This is the intent of the Workshop on Sensor-Based Robots: Algorithms and Architectures - to study the fundamental research issues and problems associated with sensor-based robot manipulators and to propose approaches and solutions from various viewpoints in improving present day robot manipulators in the areas of sensor fusion and integration, sensory information processing, and parallel algorithms and architectures for robotic computations.

Internet usage has become a facet of everyday life, especially as more technological advances have made it easier to connect to the web from virtually anywhere in the developed world. However, with this

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increased usage comes heightened threats to security within digital environments. The Handbook of Research on Modern Cryptographic Solutions for Computer and Cyber Security identifies emergent research and techniques being utilized in the field of cryptology and cyber threat prevention. Featuring theoretical perspectives, best practices, and future research directions, this handbook of research is a vital resource for professionals, researchers, faculty members, scientists, graduate students, scholars, and software developers interested in threat identification and prevention.

The focus of the workshop was on recent advances in the theory, applications and techniques for distributed computer control systems. Topics included: tools and methods for inner layers of DCCS; application papers presenting operational DCCS; the infiltration of

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true real-time or "time critical" concepts and the emergence of artificial intelligence methods in DCCS applications, leading to novel computer architectures being integrated in computer networks. The book will be of interest not only to those involved in DCCS but also software engineers and distributed computing scientists.

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