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ENGINEERING MECHANICS: STATICS, 4E, written by authors Andrew Pytel and Jaan Kiusalaas, provides readers with a solid understanding of statics without the overload of extraneous detail. The authors use their extensive teaching experience and first-hand knowledge to deliver a presentation that's ideally suited to the skills of today's learners. This edition clearly introduces critical concepts using features that connect real problems and examples with the fundamentals of engineering mechanics. Readers learn how to effectively analyze problems before substituting numbers into formulas -- a skill that will benefit them

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Intended as an introduction to robot mechanics for students of mechanical, industrial, electrical, and bio-mechanical engineering, this graduate text presents a wide range of approaches and topics. It avoids formalism and proofs but nonetheless discusses advanced concepts and contemporary applications. It will thus also be of interest to practicing engineers. The book begins with kinematics, emphasizing an approach based on rigid-body displacements instead of coordinate transformations; it then turns to inverse kinematic analysis, presenting the widely used Pieper-Roth and zero-reference-position methods. This is followed by a discussion of workplace characterization and determination. One focus of the discussion is the motion made possible by spherical and other novel wrist designs. The text concludes with a brief discussion of dynamics and control. An extensive bibliography provides access to the current literature.

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