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English. The Supplement adds approximately 40,000 new entries.

"Who were the pioneers in science education, and what motivated them to do what they did?" This book is the second volume of an attempt to capture and record some of the answers to these questions—either from the pioneers themselves or from those persons who worked most closely with them. As with the first volume, we have attempted to include as many pioneers as possible, but we know that there are still many that are not included in this or the previous volume. As we have posed questions, rummaged through files and oft-neglected books, and probed the memories of many individuals, we have come to realize our list of true pioneers is ever growing. As

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we consider our list of pioneers, we know that there are names on the list that most of us readily recognize. We also fully realize that there are names of whom few of us have heard—yet who were significant in their roles as mentors or idea development and teaching. We continue to be impressed with our science education “family tree” ever branching out to more individuals and connections. The stories in this volume continue to demonstrate how vital this network was in supporting the individual pioneers during their journey in difficult times and continues to be for those of us today in our own enterprise.

Control and Dynamic Systems: Advances in Theory and Applications, Volume 50: Robust Control System Techniques and Applications, Part 1 of 2 is a two-volume sequence devoted to the issues and application of robust control systems

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techniques. This volume is composed of 10 chapters and begins with a presentation of the important techniques for dealing with conflicting design objectives in control systems. The subsequent chapters describe the robustness techniques of systems using differential-difference equations; the design of a wide class of robust nonlinear systems, the techniques for dealing with the problems resulting from the use of observers in robust systems design, and the effective techniques for the robust control on non-linear time varying of tracking control systems with uncertainties. These topics are followed by discussions of the effective techniques for the robust control on non-linear time varying of tracking control systems with uncertainties and for incorporating adaptive control techniques into a (non-adaptive) robust control design. Other chapters present techniques

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for achieving exponential and robust stability for a rather general class of nonlinear systems, techniques in modeling uncertain dynamics for robust control systems design, and techniques for the optimal synthesis of these systems. The last chapters provide a generalized eigenproblem solution for both singular and nonsingular system cases. These chapters also look into the stability robustness design for discrete-time systems. This book will be of value to process and systems engineers, designers, and researchers.

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